# Exponential stability for impulsive functional differential equations with infinite delay

## Teresa Faria, Marta C. Gadotti, and José J. Oliveira<sup>a</sup>

July 4, 2012

(*a*) Departamento de Matemática e Aplicações, CMAT, Universidade do Minho

イロト イポト イヨト イヨト

## Impulsive ordinary differential equations

► IVP of impulsive ordinary differential equations:

$$\begin{cases} x'(t) = f(t, x(t)), & 0 \le t \ne t_k \\ \Delta x(t_k) = l_k(x(t_k)), & k = 1, 2, \cdots, \\ x(0) = x_0 \in \mathbb{R}^n, \end{cases}$$
(1)

where

- 4 同 6 4 日 6 4 日 6

# Impulsive ordinary differential equations

IVP of impulsive ordinary differential equations:

$$\begin{cases} x'(t) = f(t, x(t)), & 0 \le t \ne t_k \\ \Delta x(t_k) = l_k(x(t_k)), & k = 1, 2, \cdots, \\ x(0) = x_0 \in \mathbb{R}^n, \end{cases}$$
(1)

where

$$\Delta x(t_k) := x(t_k^+) - x(t_k^-);$$

- $f: [0, +\infty) \times \mathbb{R}^n \to \mathbb{R}^n$  and  $I_k : \mathbb{R}^n \to \mathbb{R}^n$  are cont. functions;
- $(t_k)_{k\in\mathbb{N}}\nearrow +\infty$  as  $k\to +\infty$ .
- A function  $x : [0, d] \to \mathbb{R}^n$  is a solution of (1) if
  - it is continuous on  $[0, d] \setminus \{t_k : k \in \mathbb{N}\}$ ,
  - $x(t_k^-)$  and  $x(t_k^+)$  exist with  $x(t_k^-) = x(t_k)$
  - satisfies (1).

イロト イポト イラト イラト 一日

## Impulsive delay differential equations

Impulsive functional differential equations:

$$\begin{cases} x'(t) = f(t, x_t), & 0 \le t \ne t_k \\ \Delta x(t_k) = I_k(x_{t_k}), & k = 1, 2, \cdots \end{cases}$$
(2)

where

• 
$$x_t(s) = x(t+s)$$
, for  $s \in (-\infty, 0]$ ;

•  $f : [0, +\infty) \times \mathcal{PS} \to \mathbb{R}^n$  and  $I_k : \mathcal{PS} \to \mathbb{R}^n$  are continuous.

With  $\mathcal{PS}$  a convenient Phase Space of functions  $\phi: (-\infty, 0] \to \mathbb{R}^n$ .

## Impulsive delay differential equations

Impulsive functional differential equations:

$$\begin{cases} x'(t) = f(t, x_t), & 0 \le t \ne t_k \\ \Delta x(t_k) = I_k(x_{t_k}), & k = 1, 2, \cdots \end{cases}$$
(2)

where

• 
$$x_t(s) = x(t+s)$$
, for  $s \in (-\infty, 0]$ ;

•  $f : [0, +\infty) \times \mathcal{PS} \to \mathbb{R}^n$  and  $I_k : \mathcal{PS} \to \mathbb{R}^n$  are continuous.

With  $\mathcal{PS}$  a convenient Phase Space of functions

$$\phi:(-\infty,0]\to\mathbb{R}^n.$$

▶ We consider Bounded Initial Conditions:

$$x_0 = \phi \in B\mathcal{PS}$$
, (bounded functions on  $\mathcal{PS}$ ). (3)

イロト イポト イヨト イヨト 二日

## \*Phase Space

[γ, β] compact interval of ℝ, PC([γ, β]; ℝ<sup>n</sup>) space of functions
 φ: [γ, β] → ℝ<sup>n</sup> continuous except for a finite points s,
 φ(s<sup>-</sup>), φ(s<sup>+</sup>) exist, and φ(s<sup>-</sup>) = φ(s);

## \*Phase Space

- [γ, β] compact interval of ℝ, PC([γ, β]; ℝ<sup>n</sup>) space of functions φ : [γ, β] → ℝ<sup>n</sup> continuous except for a finite points s, φ(s<sup>-</sup>), φ(s<sup>+</sup>) exist, and φ(s<sup>-</sup>) = φ(s);
- R([γ, β]; ℝ<sup>n</sup>) = PC([γ, β]; ℝ<sup>n</sup>) on the space of bounded functions with sup norm;

#### Phase Space Impulsive neural network model with infinite delays

## \*Phase Space

- [γ, β] compact interval of ℝ, PC([γ, β]; ℝ<sup>n</sup>) space of functions
   φ: [γ, β] → ℝ<sup>n</sup> continuous except for a finite points s,
   φ(s<sup>-</sup>), φ(s<sup>+</sup>) exist, and φ(s<sup>-</sup>) = φ(s);
- R([γ, β]; ℝ<sup>n</sup>) = PC([γ, β]; ℝ<sup>n</sup>) on the space of bounded functions with sup norm;

$$\mathsf{PC} := \mathsf{PC}((-\infty,\beta];\mathbb{R}^n) = \left\{ \phi : (-\infty,0] \to \mathbb{R}^n |\phi|_{[\gamma,\beta]} \in \mathsf{R}([\gamma,\beta];\mathbb{R}^n), \forall [\gamma,\beta] \subseteq (-\infty,0] \right\};$$

## \*Phase Space

- $[\gamma, \beta]$  compact interval of  $\mathbb{R}$ ,  $PC([\gamma, \beta]; \mathbb{R}^n)$  space of functions  $\phi : [\gamma, \beta] \to \mathbb{R}^n$  continuous except for a finite points s,  $\phi(s^-), \phi(s^+)$  exist, and  $\phi(s^-) = \phi(s)$ ;
- R([γ, β]; ℝ<sup>n</sup>) = PC([γ, β]; ℝ<sup>n</sup>) on the space of bounded functions with sup norm;

► 
$$PC := PC((-\infty, \beta]; \mathbb{R}^n) =$$
  
 $\left\{ \phi : (-\infty, 0] \to \mathbb{R}^n | \phi_{|[\gamma, \beta]} \in R([\gamma, \beta]; \mathbb{R}^n), \forall [\gamma, \beta] \subseteq (-\infty, 0] \right\};$   
► For  $\alpha > 0$ ,

$$\mathsf{PC}_lpha := \left\{ \phi \in \mathsf{PC} : \sup_{s \leq 0} |\phi(s)| e^{lpha s} < \infty 
ight\}$$

$$\|\phi\|_{lpha} = \sup_{s \le 0} |\phi(s)| e^{lpha s}, \text{ with } |x| = |(x_1, \dots, x_n)| = \max_{1 \le i \le n} |x_i|$$

#### Phase Space Impulsive neural network model with infinite delays

## \*Phase Space

- [γ, β] compact interval of ℝ, PC([γ, β]; ℝ<sup>n</sup>) space of functions
   φ: [γ, β] → ℝ<sup>n</sup> continuous except for a finite points s,
   φ(s<sup>-</sup>), φ(s<sup>+</sup>) exist, and φ(s<sup>-</sup>) = φ(s);
- R([γ, β]; ℝ<sup>n</sup>) = PC([γ, β]; ℝ<sup>n</sup>) on the space of bounded functions with sup norm;

► 
$$PC := PC((-\infty, \beta]; \mathbb{R}^n) =$$
  
 $\left\{ \phi : (-\infty, 0] \to \mathbb{R}^n |\phi|_{[\gamma, \beta]} \in R([\gamma, \beta]; \mathbb{R}^n), \forall [\gamma, \beta] \subseteq (-\infty, 0] \right\};$   
► For  $\alpha > 0$ ,

$$\mathcal{PC}_{lpha} := \left\{ \phi \in \mathcal{PC} : \sup_{s \leq 0} |\phi(s)| e^{lpha s} < \infty 
ight\}$$

$$\|\phi\|_{lpha} = \sup_{s \leq 0} |\phi(s)| e^{lpha s}, \text{ with } |x| = |(x_1, \dots, x_n)| = \max_{1 \leq i \leq n} |x_i|$$

 $\blacktriangleright \mathcal{PS} = \mathcal{PC}_{\alpha}$ 

$$BPC_{\alpha} = \{ \phi \in PC_{\alpha} : \phi \text{ bounded } \}.$$

\***Theorem** (Existence of solutions) If

- ▶  $t \to f(t, x_t)$  measurable on  $(0, +\infty]$ , for  $x : \mathbb{R} \to \mathbb{R}^n$  bounded;
- ▶  $\exists p, q : [0, +\infty) \rightarrow [0, \infty)$  continuous with q non-decreasing, q(u)u > 0, and  $\int^{\infty} \frac{1}{q} = \infty$  such that

 $|f(t,\psi)| \le p(t)q(\|\psi\|), \quad t \ge 0, \psi \in BPC_{\alpha};$ 

►  $I_k(X)$  is bounded for all  $X \subseteq BPC_{\alpha}$  bounded. then, the PVI (2)-(3) has a solution x(t) defined on  $[0, +\infty)$ .

イロト イポト イラト イラト 一日

$$\begin{cases} x_{i}'(t) = -a_{i}(x_{i}(t))[b_{i}(x_{i}(t)) + f(t, x_{t})], & 0 \leq t \neq t_{k}, \\ \Delta(x_{i}(t_{k})) = I_{ik}(x_{i}(t_{k}^{-})), & i = 1, \cdots, n, \quad k = 1, 2, \cdots \end{cases}$$
(4)

<ロ> (四) (四) (三) (三) (三)

$$\begin{cases} x_i'(t) = -a_i(x_i(t))[b_i(x_i(t)) + f(t, x_t)], & 0 \le t \ne t_k, \\ \Delta(x_i(t_k)) = I_{ik}(x_i(t_k^-)), & i = 1, \cdots, n, \quad k = 1, 2, \cdots \end{cases}$$
(4)

(A1)  $a_i: \mathbb{R} \to (0, +\infty)$ , continuous and  $a_i(u) \geq \underline{a_i} > 0, \forall u;$ 

$$\begin{cases} x_i'(t) = -a_i(x_i(t))[b_i(x_i(t)) + f(t, x_t)], & 0 \le t \ne t_k, \\ \Delta(x_i(t_k)) = I_{ik}(x_i(t_k^-)), & i = 1, \cdots, n, & k = 1, 2, \cdots \end{cases}$$
(4)

(A1)  $a_i : \mathbb{R} \to (0, +\infty)$ , continuous and  $a_i(u) \ge \underline{a_i} > 0$ ,  $\forall u$ ; (A2)  $b_i : \mathbb{R} \to \mathbb{R}$  continuous such that

$$rac{b_i(u)-b_i(v)}{u-v} \geq eta_i > 0, \quad \forall u 
eq v;$$

$$\begin{cases} x_i'(t) = -a_i(x_i(t))[b_i(x_i(t)) + f(t, x_t)], & 0 \le t \ne t_k, \\ \Delta(x_i(t_k)) = I_{ik}(x_i(t_k^-)), & i = 1, \cdots, n, & k = 1, 2, \cdots \end{cases}$$
(4)

(A1)  $a_i : \mathbb{R} \to (0, +\infty)$ , continuous and  $a_i(u) \ge \underline{a_i} > 0$ ,  $\forall u$ ; (A2)  $b_i : \mathbb{R} \to \mathbb{R}$  continuous such that

$$\frac{b_i(u)-b_i(v)}{u-v} \geq \beta_i > 0, \quad \forall u \neq v;$$

(A3)  $|f_i(t,\varphi) - f_i(t,\phi)| \le I_i ||\varphi - \phi||_{\alpha}, \forall t \ge 0, \forall \varphi, \phi \in PC_{\alpha};$ 

$$\begin{cases} x_i'(t) = -a_i(x_i(t))[b_i(x_i(t)) + f(t, x_t)], & 0 \le t \ne t_k, \\ \Delta(x_i(t_k)) = I_{ik}(x_i(t_k^-)), & i = 1, \cdots, n, & k = 1, 2, \cdots \end{cases}$$
(4)

(A1)  $a_i : \mathbb{R} \to (0, +\infty)$ , continuous and  $a_i(u) \ge \underline{a_i} > 0, \forall u$ ; (A2)  $b_i : \mathbb{R} \to \mathbb{R}$  continuous such that

$$\frac{b_i(u)-b_i(v)}{u-v} \geq \beta_i > 0, \quad \forall u \neq v;$$

 $\begin{array}{l} (\mathsf{A3}) \ |f_i(t,\varphi) - f_i(t,\phi)| \leq I_i \|\varphi - \phi\|_{\alpha}, \ \forall t \geq 0, \ \forall \varphi, \phi \in \mathcal{PC}_{\alpha}; \\ (\mathsf{A4}) \ \beta_i > I_i, \ \forall i; \end{array}$ 

$$\begin{cases} x_i'(t) = -a_i(x_i(t))[b_i(x_i(t)) + f(t, x_t)], & 0 \le t \ne t_k, \\ \Delta(x_i(t_k)) = I_{ik}(x_i(t_k^-)), & i = 1, \cdots, n, & k = 1, 2, \cdots \end{cases}$$
(4)

(A1)  $a_i : \mathbb{R} \to (0, +\infty)$ , continuous and  $a_i(u) \ge \underline{a_i} > 0, \forall u$ ; (A2)  $b_i : \mathbb{R} \to \mathbb{R}$  continuous such that

$$\frac{b_i(u)-b_i(v)}{u-v} \geq \beta_i > 0, \quad \forall u \neq v;$$

 $\begin{array}{l} (\text{A3}) \quad |f_i(t,\varphi) - f_i(t,\phi)| \leq I_i \|\varphi - \phi\|_{\alpha}, \ \forall t \geq 0, \ \forall \varphi, \phi \in PC_{\alpha}; \\ (\text{A4}) \quad \beta_i > I_i, \ \forall i; \\ (\text{A5}) \quad |\hat{I}_{ik}(u) - \hat{I}_{ik}(v)| \leq \hat{\gamma}_{ik} |u - v| \ \text{with} \ \hat{I}_{ik}(u) = u + I_{ik}(u). \end{array}$ 

$$x_0 = \phi \in BPC_\alpha \tag{5}$$

has a solution x(t) defined on  $[0, +\infty)$ .

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 善臣 の久で

$$x_0 = \phi \in BPC_\alpha \tag{5}$$

has a solution x(t) defined on  $[0, +\infty)$ .

\* **Proposition:** Assume (A2), (A3), and (A4). If  $t \to f_i(t, x)$  are constant, for each  $x \in \mathbb{R}^n$ , then  $\exists^1 x^* = (x_1^*, \dots, x_n^*) \in \mathbb{R}^n$  equilibrium point of non-impulsive model (4).

◆□ > ◆□ > ◆臣 > ◆臣 > ─ 臣 ─ のへで

$$x_0 = \phi \in BPC_\alpha \tag{5}$$

has a solution x(t) defined on  $[0, +\infty)$ .

- \* **Proposition:** Assume (A2), (A3), and (A4). If  $t \to f_i(t, x)$  are constant, for each  $x \in \mathbb{R}^n$ , then  $\exists^1 x^* = (x_1^*, \dots, x_n^*) \in \mathbb{R}^n$  equilibrium point of non-impulsive model (4).
- \* Assumption: We assume that

$$I_{ik}(x_i^*)=0, \quad i=1,\ldots,n, \ \forall k.$$

and  $x^*$  is called the equilibrium point of (4).

イロト イポト イラト イラト 一日

$$x_0 = \phi \in BPC_\alpha \tag{5}$$

has a solution x(t) defined on  $[0, +\infty)$ .

- \* **Proposition:** Assume (A2), (A3), and (A4). If  $t \to f_i(t, x)$  are constant, for each  $x \in \mathbb{R}^n$ , then  $\exists^1 x^* = (x_1^*, \dots, x_n^*) \in \mathbb{R}^n$  equilibrium point of non-impulsive model (4).
- \* Assumption: We assume that

$$I_{ik}(x_i^*)=0, \quad i=1,\ldots,n, \ \forall k.$$

and  $x^*$  is called the equilibrium point of (4).

\* **Definition:** The equilibrium point  $x^* \in \mathbb{R}^n$  is said global exponential stable if exists  $M, \epsilon > 0$ :

$$|x(t,0,\phi)-x^*|\leq Me^{-\epsilon t}\|\phi-x^*\|_lpha, \quad orall t\geq 0, \phi\in BPC_lpha.$$

#### Lemma:

Assume (A2), (A3), and  $x^* = (0, ..., 0)$  equilibrium of (4). Let  $x : (-\infty, b] \to \mathbb{R}^n$ , b > a, a solution of non-impulsive equation of (4) on [a, b], with  $x_a \in PC_{\alpha}$ . If exists c > 0 and  $\epsilon \in (0, \alpha]$ , with  $\epsilon < \min_i \{\underline{a_i}(\beta_i - l_i)\}$ , such that

$$|x(t)| \leq c e^{-\epsilon(t-a)}, \quad ext{ for } \quad t \leq a,$$

than

$$|x(t)| \leq c e^{-\epsilon(t-a)}, \quad \text{for} \quad t \leq b.$$
 (6)

イロト イポト イヨト イヨト

## Proof (idea)

By contradition, assume that (6) does not hold. Then there are  $\delta > 0$ ,  $m \in \{1, ..., n\}$ ,  $t^* \in (a, b]$ :

$$|x_m(t^*)| = (c+\delta)e^{-\epsilon(t^*-a)}$$
 and  $|x_i(t)| < (c+\delta)e^{-\epsilon(t-a)},$ 

for all  $t < t^*$  and  $i = 1, \ldots, n$ .

・ロト ・回ト ・ヨト ・ヨト

## Proof (idea)

By contradition, assume that (6) does not hold. Then there are  $\delta > 0$ ,  $m \in \{1, ..., n\}$ ,  $t^* \in (a, b]$ :

$$|\mathsf{x}_m(t^*)| = (c+\delta)e^{-\epsilon(t^*-\mathsf{a})}$$
 and  $|\mathsf{x}_i(t)| < (c+\delta)e^{-\epsilon(t-\mathsf{a})},$ 

for all  $t < t^*$  and  $i = 1, \ldots, n$ .

► Consider the function  $y(t) := (c + \delta)e^{-\epsilon(t-a)}$ ,  $t \in [a, b]$ . Assuming  $x_m(t^*) > 0$  (analogous if  $x_m(t^*) < 0$ ), we have

 $x_m'(t^*) \geq y'(t^*).$ 

## Proof (idea)

By contradition, assume that (6) does not hold. Then there are  $\delta > 0$ ,  $m \in \{1, ..., n\}$ ,  $t^* \in (a, b]$ :

$$|x_m(t^*)| = (c+\delta)e^{-\epsilon(t^*-a)}$$
 and  $|x_i(t)| < (c+\delta)e^{-\epsilon(t-a)},$ 

for all  $t < t^*$  and  $i = 1, \ldots, n$ .

Consider the function y(t) := (c + δ)e<sup>-ϵ(t-a)</sup>, t ∈ [a, b]. Assuming x<sub>m</sub>(t<sup>\*</sup>) > 0 (analogous if x<sub>m</sub>(t<sup>\*</sup>) < 0), we have</p>

$$x'_m(t^*) \geq y'(t^*).$$

On the other hand, using hypotheses, we have

$$\begin{array}{ll} x'_{m}(t^{*}) &=& -a_{m}(x_{m}(t^{*}))[b_{m}(x_{m}(t^{*}))+f_{m}(t^{*},y_{t^{*}})] \\ &\leq& -\underline{a_{m}}[\beta_{m}x_{m}(t^{*})-I_{m}\|x_{t^{*}}\|_{\alpha}] \\ &\leq& -\underline{a_{m}}[\beta_{m}y(t^{*})-I_{m}\sup_{s\leq 0}(c+\delta)e^{-\epsilon(t^{*}+s-a)+\alpha s}] \\ &\leq& -\underline{a_{m}}(\beta_{m}-I_{m})y(t^{*})<-\epsilon z(t^{*})=y'(t^{*}) \end{array}$$

Impulsive delay differential equation Global asymptotic stability Preliminary lemma Main result Application

## Theorem

▶ Assume hypotheses (A1)-(A5), and (A6) for some  $k_0 \in \mathbb{N}$  and  $\hat{\gamma}_k := \max_i \hat{\gamma}_{ik}$ ,

$$\eta := \sup_{k \ge k_0} \left( \frac{\log(\max\{1, \hat{\gamma}_k\})}{t_k - t_{k-1}} \right) < \alpha < \min_i \{ \underline{a_i}(\beta_i - l_i) \}.$$
(7)

If  $x^*$  is the equilibrium point of (4), then it is globally exponentially stable.

イロン イヨン イヨン イヨン

Impulsive delay differential equation Global asymptotic stability Preliminary lemma Main result Application

## Theorem

▶ Assume hypotheses (A1)-(A5), and (A6) for some  $k_0 \in \mathbb{N}$  and  $\hat{\gamma}_k := \max_i \hat{\gamma}_{ik}$ ,

$$\eta := \sup_{k \ge k_0} \left( \frac{\log(\max\{1, \hat{\gamma}_k\})}{t_k - t_{k-1}} \right) < \alpha < \min_i \{ \underline{a_i}(\beta_i - l_i) \}.$$
(7)

If  $x^*$  is the equilibrium point of (4), then it is globally exponentially stable.

Notes:

- The situation  $\hat{\gamma}_k > 1$ , for large k, is especially relevant.
- It is frequent in the literature:

$$I_{ik}(u) = -\alpha_{ik}(u - x_i^*), \quad \text{ with } 0 < \alpha_{ik} < 2,$$

which implies

$$|x_i(t_k^+) - x_i^*| < |x_i(t_k) - x_i^*|.$$

イロト イポト イヨト イヨト

## Proof (idea)

Suppose that  $x^* = (0, ..., 0)$  and write  $\eta_k = \max\{1, \hat{\gamma}_k\}$ . Let x(t) solution of (4) defined on  $\mathbb{R}$ , with  $x_0 \in PC_{\alpha}$ .

Impulsive delay differential equation Global asymptotic stability Preliminary lemma Main result Application

## Proof (idea)

Suppose that  $x^* = (0, ..., 0)$  and write  $\eta_k = \max\{1, \hat{\gamma}_k\}$ . Let x(t) solution of (4) defined on  $\mathbb{R}$ , with  $x_0 \in PC_{\alpha}$ .

Consequently, we have

$$|x(t)| \leq ||x_0||_{lpha} e^{-lpha t}, \quad ext{ for } \quad t \in (-\infty, 0],$$

and, by Lemma, we have

$$|x(t)| \leq ||x_0||_{lpha} e^{-lpha t}, \quad ext{ for } \quad t \in (-\infty, t_1].$$

イロト イヨト イヨト イヨト

Impulsive delay differential equation Global asymptotic stability Preliminary lemma Main result Application

## Proof (idea)

Suppose that  $x^* = (0, ..., 0)$  and write  $\eta_k = \max\{1, \hat{\gamma}_k\}$ . Let x(t) solution of (4) defined on  $\mathbb{R}$ , with  $x_0 \in PC_{\alpha}$ .

Consequently, we have

$$|x(t)| \leq ||x_0||_{lpha} e^{-lpha t}, \quad ext{ for } \quad t \in (-\infty, 0],$$

and, by Lemma, we have

$$|x(t)| \leq \|x_0\|_{lpha} e^{-lpha t}, \quad ext{ for } \quad t \in (-\infty, t_1].$$

► For some *i*,

$$|x(t_1^+)| = |x_i(t_1^+)| = |\hat{l}_{i1}(x_i(t_1))| \le \hat{\gamma}_{i1}|x_i(t_1)| \le \eta_1 \|x_0\|_lpha e^{-lpha t_1}$$
. Thus

$$|x(t)|\leq \eta_1\|x_0\|_lpha e^{-lpha t_1}e^{-lpha(t-t_1)}, \quad ext{ for } \quad t\in(-\infty,t_1^+],$$

and, again by the Lemma,

$$|x(t)| \leq \eta_1 \|x_0\|_{lpha} e^{-lpha t}, \quad ext{ for } \quad t \in (-\infty, t_2].$$

イロン イ部ン イヨン イヨン 三日

Iterating the process, we have

$$|\mathbf{x}(t)| \leq \eta_1 \eta_2 \dots \eta_{k-1} \|\mathbf{x}_0\|_{lpha} e^{-lpha t}, \quad ext{ for } t \in (t_{k-1}, t_k], \ k = 1, 2, \cdots.$$

From **(A6)** we have  $\eta_k \leq e^{\eta(t_k-t_{k-1})}$ , for all  $k \geq k_0$ . Thus, for  $t \in (t_{k-1}, t_k]$  and  $k > k_0$ ,

$$\begin{aligned} |x(t)| &\leq \eta_1 \eta_2 \dots \eta_{k_0-1} \|x_0\|_{\alpha} e^{\eta t_{k-1}} e^{-\alpha t} \\ &\leq \eta_1 \eta_2 \dots \eta_{k_0-1} \|x_0\|_{\alpha} e^{-(\alpha-\eta)t}, \end{aligned}$$

which implies

$$|x(t) - x^*| \leq \eta_1 \eta_2 \dots \eta_{k_0-1} ||x_0 - x^*||_{\alpha} e^{-(\alpha - \eta)t}, \quad t \geq 0.$$

イロト イヨト イヨト イヨト

## Impulsive general Cohen-Grossberg neural network

$$\begin{aligned} x_{i}'(t) &= -a_{i}(x_{i}(t)) \bigg[ b_{i}(x_{i}(t)) - \sum_{j=1}^{n} \sum_{p=1}^{P} \bigg( h_{ij}^{(p)}(x_{j}(t - \tau_{ij}^{(p)}(t))) \\ &+ f_{ij}^{(p)} \bigg( \int_{-\infty}^{0} g_{ij}^{(p)}(x_{j}(t + s)) d\eta_{ij}^{(p)}(s) \bigg) \bigg) \bigg], \ 0 \geq t \neq t_{k}, \\ \Delta(x_{i}(t_{k})) &= I_{ik}(x_{i}(t_{k}^{-})), \ i = 1, \dots, n, \ k \in \mathbb{N}, \end{aligned}$$

$$(8)$$

▶  $a_i : \mathbb{R} \to (0, +\infty)$ , are continuous satisfying **(A1)**;

(ロ) (同) (E) (E) (E)

## Impulsive general Cohen-Grossberg neural network

$$\begin{aligned} x_{i}'(t) &= -a_{i}(x_{i}(t)) \bigg[ b_{i}(x_{i}(t)) - \sum_{j=1}^{n} \sum_{p=1}^{P} \bigg( h_{ij}^{(p)}(x_{j}(t - \tau_{ij}^{(p)}(t))) \\ &+ f_{ij}^{(p)} \bigg( \int_{-\infty}^{0} g_{ij}^{(p)}(x_{j}(t + s)) d\eta_{ij}^{(p)}(s) \bigg) \bigg) \bigg], \ 0 \geq t \neq t_{k}, \\ \Delta(x_{i}(t_{k})) &= I_{ik}(x_{i}(t_{k}^{-})), \ i = 1, \dots, n, \ k \in \mathbb{N}, \end{aligned}$$

a<sub>i</sub>: ℝ → (0, +∞), are continuous satisfying (A1);
b<sub>i</sub>: ℝ → ℝ are continuous satisfying (A2);

イロト イポト イラト イラト 一日

## Impulsive general Cohen-Grossberg neural network

$$\begin{aligned} x_{i}'(t) &= -a_{i}(x_{i}(t)) \bigg[ b_{i}(x_{i}(t)) - \sum_{j=1}^{n} \sum_{p=1}^{P} \bigg( h_{ij}^{(p)}(x_{j}(t - \tau_{ij}^{(p)}(t))) \\ &+ f_{ij}^{(p)} \bigg( \int_{-\infty}^{0} g_{ij}^{(p)}(x_{j}(t + s)) d\eta_{ij}^{(p)}(s) \bigg) \bigg) \bigg], \ 0 \geq t \neq t_{k}, \\ \Delta(x_{i}(t_{k})) &= I_{ik}(x_{i}(t_{k}^{-})), \ i = 1, \dots, n, \ k \in \mathbb{N}, \end{aligned}$$

## Impulsive general Cohen-Grossberg neural network

$$\begin{aligned} x_{i}'(t) &= -a_{i}(x_{i}(t)) \bigg[ b_{i}(x_{i}(t)) - \sum_{j=1}^{n} \sum_{p=1}^{P} \bigg( h_{ij}^{(p)}(x_{j}(t - \tau_{ij}^{(p)}(t))) \\ &+ f_{ij}^{(p)} \bigg( \int_{-\infty}^{0} g_{ij}^{(p)}(x_{j}(t + s)) d\eta_{ij}^{(p)}(s) \bigg) \bigg) \bigg], \ 0 \geq t \neq t_{k}, \\ \Delta(x_{i}(t_{k})) &= I_{ik}(x_{i}(t_{k}^{-})), \ i = 1, \dots, n, \ k \in \mathbb{N}, \end{aligned}$$

$$(8)$$

José J. Oliveira Exponential Stability of impulsive differential equations

## Corollary

Consider (8) under the hypotheses above. In addiction, consider  $\eta_{ij}^{(p)}: (-\infty, 0] \to \mathbb{R}$  non-decreasing bounded functions so that

$$\eta_{ij}^{({m 
ho})}(0) - \eta_{ij}^{({m 
ho})}(-\infty) = 1, \,\, {
m and} \,\, \int_{-\infty}^{0} e^{-\gamma s} d\eta_{ij}^{({m 
ho})} < \infty,$$

for some  $\gamma > \eta$ . If

$$M = diag\left(\beta_1 - \frac{\eta}{\underline{a_1}}, \dots, \beta_n - \frac{\eta}{\underline{a_n}}\right) - [n_{ij}]$$

is a M-matrix, then there is a unique equilibrium point  $x^*$  of (8) which is globally exponential stable.

イロト イポト イヨト イヨト

## Corollary

Consider (8) under the hypotheses above. In addiction, consider  $\eta_{ij}^{(p)}: (-\infty, 0] \to \mathbb{R}$  non-decreasing bounded functions so that

$$\eta_{ij}^{(p)}(0) - \eta_{ij}^{(p)}(-\infty) = 1, \,\, ext{and} \,\, \int_{-\infty}^{0} e^{-\gamma s} d\eta_{ij}^{(p)} < \infty,$$

for some  $\gamma > \eta$ . If

$$M = diag\left(\beta_1 - \frac{\eta}{\underline{a_1}}, \dots, \beta_n - \frac{\eta}{\underline{a_n}}\right) - [n_{ij}]$$

is a M-matrix, then there is a unique equilibrium point  $x^*$  of (8) which is globally exponential stable.

• 
$$n_{ij} = \sum_{p=1}^{P} \left( \zeta_{ij}^{(p)} e^{\eta \tau_{ij}^{(p)}} + \mu_{ij}^{(p)} \sigma_{ij}^{(p)} \int_{-\infty}^{0} e^{-\eta s} d\eta_{ij}^{(p)}(s) \right)$$

Impulsive delay differential equation Global asymptotic stability	Preliminary lemma Main result <b>Application</b>
--	--

## Thank you

・ロン ・四 と ・ ヨ と ・ モ と