Stability of discrete-time Hopfield neural network with delay

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Generalized Hopfield model | Continuous Hopfield model

$$x_i'(t) = -a_i(t)x_i(t) + \sum_{j=1}^{N} k_{ij}(t, x_j(t - \alpha_{ij}(t))), \quad t \geqslant 0, \ i = 1, \dots, N$$

Generalized Hopfield model | Continuous Hopfield model

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neuron state vector at time t

$$(x_1(t),\ldots,x_N(t))\in\mathbb{R}^N$$

neuron charging time

$$a_i: \mathbb{R}_0^+ \to \mathbb{R}_0^+$$
 continuous

neuron activation functions

 $k_{ij}: \mathbb{R}_0^+ \times \mathbb{R} \to \mathbb{R}$ continuous, Lip on the second variable

time delay

 $\alpha_{ii}: \mathbb{R}_0^+ \to \mathbb{R}_0^+$ continuous, bounded



$$x_{i}'(t) = -a_{i}(t)x_{i}(t) + \sum_{j=1}^{N} k_{ij}(t, x_{j}(t - \alpha_{ij}(t)))$$

$$x'_{i}(t) = -a_{i}(t)x_{i}(t) + \sum_{j=1}^{N} k_{ij}(t, x_{j}(t - \alpha_{ij}(t)))$$

Discretization method in:

S. Mohamad, K. Gopalsamy, Exponential stability of continuous-time and discrete-time cellular neural networks with delays, Appl. Math. Comput. 135 (1) (2003) 17–38

$$x_{i}'(t) = -a_{i}(t)x_{i}(t) + \sum_{j=1}^{N} k_{ij}(t, x_{j}(t - \alpha_{ij}(t)))$$

$$x_i'(t) = -a_i([t/h]h)x_i(t) + \sum_{j=1}^{N} k_{ij} \left([t/h]h, x_j \left([t/h]h - \left[\frac{\alpha_{ij} \left([t/h]h \right)}{h} \right] h \right) \right)$$

$$\forall m \in \mathbb{N}_0, \ t \in [mh, (m+1)h[\ \Rightarrow \ [t/h] = m; \quad \tau_{ij}(m) := \left[\frac{\alpha_{ij}(mh)}{h}\right]$$

$$e^{a_i(mh)t}x_i'(t) + a_i(mh)e^{a_i(mh)t}x_i(t) = e^{a_i(mh)t}\sum_{j=1}^{N} k_{ij} (mh, x_j ((m - \tau_{ij}(m)) h))$$

$$\int_{mh}^{t} (e^{a_i(mh)s}x_i(s))'ds = \frac{e^{a_i(mh)t} - e^{a_i(mh)mh}}{a_i(mh)} \sum_{j=1}^{N} k_{ij} (mh, x_j ((m - \tau_{ij}(m)) h))$$

$$x_{i}(m+1) = e^{-a_{i}(m)h}x_{i}(m) + \frac{1 - e^{-a_{i}(m)h}}{a_{i}(m)} \sum_{j=1}^{N} k_{ij} \left(m, x_{j}(m - \tau_{ij}(m))\right)$$

$$x_i(m+1) = c_i(m)x_i(m) + \sum_{j=1}^{N} h_{ij}(m, x_j(m-\tau_{ij}(m))), \quad i = 1, \dots, N$$

- $c_i : \mathbb{N}_0 \to]0, 1[, \tau_{ij} : \mathbb{N}_0 \to \mathbb{N}_0 \text{ bounded with } \tau := \max_{i,j,m} \{\tau_{ij}(m)\}$
- $h_{ij}: \mathbb{N}_0 \times \mathbb{R} \to \mathbb{R}$ are Lip on the second variable, i.e.,

$$|h_{ij}(m,u) - h_{ij}(m,v)| \leq H_{ij}(m)|u - v|, \ \forall u, v \in \mathbb{R}, \ m \in \mathbb{N}_0.$$

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Generalizes:

$$x_i(m+1) = x_i(m) e^{-a_i(m)h} + \theta_i(m) \left(\sum_{j=1}^N b_{ij}(m) f_j(x_j(m-\tau(m))) + I_i(m) \right)$$

where
$$\theta_i(m) = \frac{1 - e^{-a_i(m)h}}{a_i(m)}$$
.

H. Xu, R. Wu, Periodicity and exponential stability of discrete-time neural networks with variable coefficients and delays, Adv. Difference Equ. (2013) 2013:226.

- $r \in \mathbb{N}_0$; $N \in \mathbb{N}$
- $I_{\mathbb{Z}} = I \cap \mathbb{Z}$, where I is a real interval
- Y Banach space with norm $|\cdot|$
- X space of $\alpha: [-r,0]_{\mathbb{Z}} \to Y$, with the norm $\|\alpha\| = \max_{j \in [-r,0]_{\mathbb{Z}}} |\alpha(j)|$
- X^N and Y^N equipped with the supremum norm
- Given $m \in \mathbb{N}_0$ and

$$\overline{x}: [-r, +\infty[\mathbb{Z} \to Y^N \\ s \mapsto (x_1(s), \dots, x_N(s))$$

define $x_{i,m} \in X$ and $\overline{x}_m \in X^N$ respectively by

$$x_{i,m}(j) = x_i(m+j), \quad j = -r, -r+1, \dots, 0, \quad i = 1, \dots, N,$$

$$\overline{x}_m(j) = \overline{x}(m+j), \quad j = -r, -r+1, \dots, 0.$$

Consider the general nonautonomous delay difference equation

$$x_i(m+1) = L^{(i)}(m)x_{i,m} + f^{(i)}(m, \overline{x}_m), \quad m \in \mathbb{N}_0, \ i = 1, \dots, N$$

- $L^{(i)}(m): X \to Y$ are bounded linear operators;
- $f^{(i)}(m,\cdot):X^N\to Y$ are Lip perturbations with $f^{(i)}(m,0)=0;$
- given $n \in \mathbb{N}_0$ and $\overline{\alpha} = (\alpha_1, \dots, \alpha_N) \in X^N$, there is a unique solution $\overline{x}(\cdot, n, \overline{\alpha}) \colon [n r, +\infty)_{\mathbb{Z}} \to Y^N$ such that $\overline{x}_n = \overline{\alpha}$;
- for $m, n \in \mathbb{N}_0$ with $m \ge n$, define the evolution operator $\overline{\mathcal{F}}_{m,n}: X^N \to X^N$ by

$$\overline{\mathcal{F}}_{m,n}(\overline{\alpha}) = \overline{x}_m(\cdot, n, \overline{\alpha}), \quad \overline{\alpha} \in X^N.$$



$$v_i(m+1) = L^{(i)}(m)v_{i,m}, \quad i = 1, \dots, N$$

- $v_{im}(j) = v_i(m+j), \quad j = -r, -r+1, \ldots, 0;$
- for $n \in \mathbb{N}_0$ and $\alpha_i \in X$, we obtain a unique solution $v_i(\cdot, n, \alpha_i) : [n - r, +\infty[\mathbb{Z} \to Y \text{ such that } v_{i,m}(\cdot, n, \alpha_i) = \alpha_i;$
- for $m, n \in \mathbb{N}_0$ with $m \ge n, i = 1, \dots, N$, define evolution operator $A_{m,n}^{(i)}:X\to X$ by

$$\mathcal{A}_{m,n}^{(i)}\alpha_i = v_{i,m}(\cdot, n, \alpha_i), \ \alpha_i \in X.$$

Lemma | Properties of $A^{(i)}(m,n)$

- $\mathcal{A}_{m,n}^{(i)}$ is linear for $m \ge n$;
- $\mathcal{A}_{mm}^{(i)} = \operatorname{Id}_{\mathbf{Y}}$:
- $\mathcal{A}_{l,m}^{(i)}\mathcal{A}_{m,n}^{(i)} = \mathcal{A}_{l,n}^{(i)}$ for $l \geqslant m$ and $m \geqslant n$.

• $\Gamma: Y \to X$ defined by $\Gamma u: [-r, 0]_{\mathbb{Z}} \to Y$ where

$$\Gamma u(j) = \begin{cases} u & \text{if } j = 0, \\ 0 & \text{if } j < 0, \end{cases}$$

• For all $\overline{\alpha} = (\alpha_1, \dots, \alpha_N) \in X^N$,

$$\mathcal{F}_{m,n}^{(i)}(\overline{\alpha}) = \mathcal{A}_{m,n}^{(i)} \alpha_i + \sum_{k=n}^{m-1} \mathcal{A}_{m,k+1}^{(i)} \Gamma f^{(i)}(k, \overline{x}_k), \quad i = 1, \dots, N$$

Lemma (Barreira & Valls 2007) | equation for
$$\mathcal{F}^{(i)}(m,n)$$

$$\overline{\mathcal{F}}_{m,n}(\overline{\alpha}) = \left(\mathcal{F}_{m,n}^{(1)}(\overline{\alpha}), \dots, \mathcal{F}_{m,n}^{(N)}(\overline{\alpha})\right)$$



Theorem Abstract result

Assume

- $f^{(i)}(m,\cdot): X^N \to Y^N$ are Lip functions with $f^{(i)}(m,0) = 0, \forall i$
- $\|\mathcal{A}_{m,n}^{(i)}\| \leqslant a_{m,n}^{(i)} \leqslant a_{m,n}', \quad m \geqslant n, \ i = 1..., N$

•
$$\lambda := \max_{i=1,\dots,N} \left[\sup_{m \geqslant n} \left\{ \frac{1}{a'_{m,n}} \sum_{k=n}^{m-1} a_{m,k+1}^{(i)} \operatorname{Lip}(f^{(i)}(k,\cdot)) a'_{k,n} \right\} \right] < 1$$

Then

$$\|\overline{\mathcal{F}}_{m,n}(\overline{\alpha})\| \leqslant \frac{1}{1-\lambda} a'_{m,n} \|\overline{\alpha}\|$$

for every $\overline{\alpha} = (\alpha_1, \dots, \alpha_N) \in X^N$ and $m \ge n \ge 0$.

Proof

Banach fixed point theorem in suitable complete metric space...

Stability of Hopfield models | Stability of the general model

Coming back to the Hopfield model

$$x_i(m+1) = c_i(m)x_i(m) + \sum_{j=1}^{N} h_{ij}(m, x_j(m-\tau_{ij}(m))), \quad i = 1, \dots, N$$

Theorem General stability for Hopfield model

Assume

•
$$a_{m,n}^{(i)} := \prod_{s=0}^{m-1} c_i(s) \leqslant a'_{m,n}, \qquad i = 1, \dots, N, \ m \geqslant n \geqslant 0$$

•
$$\lambda := \max_{i=1,\dots,N} \left[\sup_{m \geqslant n} \left\{ \frac{1}{a'_{m,n}} \sum_{k=n}^{m-1} a_{m,k+1}^{(i)} a'_{k,n} \sum_{j=1}^{N} H_{ij}(k) \right\} \right] < 1$$

Then, for every $\overline{\alpha}, \overline{\alpha}^* : [-r, 0]_{\mathbb{Z}} \to \mathbb{R}^N$ and $m \ge n \ge 0$

$$\|\overline{x}_m(\cdot, n, \overline{\alpha}) - \overline{x}_m(\cdot, n, \overline{\alpha}^*)\| \leqslant \frac{1}{1-\lambda} a'_{m,n} \|\overline{\alpha} - \overline{\alpha}^*\|$$

Stability of Hofield models | Proof of the general stability theorem

Proof

• The change $\overline{y}(m) = \overline{x}(m, n, \overline{\alpha}) - \overline{x}(m, n, \overline{\alpha}^*)$ transforms

$$x_{i}(m+1) = c_{i}(m)x_{i}(m) + \sum_{j=1}^{N} h_{ij}(m, x_{j}(m-\tau_{ij}(m))) \text{ into}$$
$$y_{i}(m+1) = c_{i}(m)y_{i}(m) + \sum_{j=1}^{N} \tilde{h}_{ij}(m, y_{j}(m-\tau_{ij}(m)))$$

- $\operatorname{Lip}(\widetilde{h}_{ij}(m,\cdot)) = H_{ij}(m)$ and $\overline{y} = 0$ is an equilibrium point
- For $Y = \mathbb{R}$, by the abstract result (previous Theorem)

$$\|\overline{y}_m(\cdot, n, \overline{\beta})\| \leqslant \frac{1}{1-\lambda} a'_{m,n} \|\overline{\beta}\|$$

• Setting $\overline{\beta} = \overline{\alpha} - \overline{\alpha}^*$, we conclude that

$$\|\overline{x}_m(\cdot, n, \overline{\alpha}) - \overline{x}_m(\cdot, n, \overline{\alpha}^*)\| = \|\overline{y}_m(\cdot, n, \overline{\alpha} - \overline{\alpha}^*)\| \leqslant \frac{1}{1 - \lambda} a'_{m,n} \|\overline{\alpha} - \overline{\alpha}^*\|$$

Stability of Hopfield models | Stability of the Xu-Wu model

$$x_i(m+1) = x_i(m) e^{-a_i(m)h} + \theta_i(m) \left(\sum_{j=1}^N b_{ij}(m) f_j(x_j(m-\tau(m))) + I_i(m) \right)$$

$$a_i^- = \inf_m a_i(m) \quad \ b_{ij}^+ = \sup_m |b_{ij}(m)| \quad \ \theta_i^+ = \sup_m \theta_i(m) \quad \ F_j \text{ Lip. constant of } f_j$$

Corollary Stability

Assume

$$a_i^- > \sum_{j=1}^N b_{ij}^+ F_j, \quad i = 1, \dots, N$$

Then

model Xu-Wu is globally exponentially stable, i.e., there are $\mu > 0$ and C > 1such that, for every $\overline{\alpha}, \overline{\alpha}^* : [-\tau, 0]_{\mathbb{Z}} \to \mathbb{R}^N, m \geqslant n \geqslant 0$,

$$\|\overline{x}_m(\cdot, n, \overline{\alpha}) - \overline{x}_m(\cdot, n, \overline{\alpha}^*)\| \leqslant C e^{-\mu(m-n)} \|\overline{\alpha} - \overline{\alpha}^*\|,$$

Stability of Hopfield models | Stability of the Xu-Wu model

Proof

- $c_i(m) = e^{-a_i(m)h} \Rightarrow a_{m,n}^{(i)} = \prod e^{-a_i(s)h} \leqslant e^{-\nu_i(m-n)} \leqslant e^{-\mu(m-n)} = a'_{m,n}$ where $\nu_i := a_i^- h$ and $0 < \mu < \min_i \nu_i$ such that
- $\frac{e^{\nu_i \mu} 1}{e^{\nu_i} 1} a_i^- > \sum_{i=1}^N b_{ij}^+ F_j$, for all $i = 1, \dots N$
- by computations we have

$$\begin{split} \lambda &= \max_{i=1,\dots,N} \left[\sup_{m \geqslant n} \left\{ \frac{1}{a'_{m,n}} \sum_{k=n}^{m-1} a'_{m,k+1} a'_{k,n} \, \theta_i(k) \sum_{j=1}^{N} |b_{ij}(k)| F_j \right\} \right] \\ &< \max_{i=1,\dots,N} \left[\sup_{m \geqslant n} \left\{ \sum_{k=n}^{m-1} \mathrm{e}^{(\nu_i - \mu)(k-m)} \right\} \, \mathrm{e}^{\nu_i} \, \, \frac{1 - \mathrm{e}^{-\nu_i}}{a_i^-} \frac{\mathrm{e}^{\nu_i - \mu} - 1}{\mathrm{e}^{\nu_i} - 1} a_i^- \right] \\ &= \max_{i=1,\dots,N} \left[\sup_{m \geqslant n} \left\{ \frac{1 - \mathrm{e}^{(\nu_i - \mu)(n-m)}}{\mathrm{e}^{\nu_i - \mu} - 1} \right\} \left(\mathrm{e}^{\nu_i - \mu} - 1 \right) \right] = 1 \end{split}$$

Corollary | Stability

Assume

$$\mathcal{M} = diag(a_1^-, \dots, a_N^-) - \left[b_{ij}^+ F_j\right]$$
 is an M-matrix

Then

model Xu-Wu is global exponential stable, i.e., there are $\mu > 0, C > 1$ such that

$$\|\overline{x}_m(\cdot, n, \overline{\alpha}) - \overline{x}_m(\cdot, n, \overline{\alpha}^*)\| \leqslant C e^{-\mu(m-n)} \|\overline{\alpha} - \overline{\alpha}^*\|.$$

for every $\overline{\alpha}, \overline{\alpha}^* : [-\tau, 0]_{\mathbb{Z}} \to \mathbb{R}^N$ and $m \ge n \ge 0$.

Stability of Hopfield models | Stability of the Xu-Hu model

Proof

• \mathcal{M} is an M-matrix \Leftrightarrow there is $\overline{d} = (d_1, \dots, d_N) > 0$ such that $\mathcal{M} \overline{d} > 0$, i.e.,

$$d_i a_i^- > \sum_{j=1}^N d_j b_{ij}^+ F_j$$

• The change $y_i(m) = d_i^{-1} x_i(m) \Rightarrow$

$$y_i(m+1) = y_i(m) e^{-a_i(m)h} + \theta_i(m) \left[\sum_{j=1}^N \tilde{b}_{ij}(m) \tilde{f}_j(y_j(m-\tau(m))) + \tilde{I}_i(m) \right]$$

where
$$\tilde{b}_{ij}(m) = d_i^{-1}b_{ij}(m)$$
, $\tilde{f}_j(u) = f_j(d_ju)$, and $\tilde{I}_i(m) = d_i^{-1}I_i(m)$

- f_j Lip with constant $F_j \Rightarrow \tilde{f}_j$ Lip with constant $\tilde{F}_j = d_j F_j$
- $a_i^- > \sum_{j=1}^N d_i^{-1} b_{ij}^+ d_j F_j \quad \Leftrightarrow \quad a_i^- > \sum_{j=1}^N \tilde{b}_{ij}^+ \tilde{F}_j$

Theorem | Existence and stability of periodic solution

Assume

- a_i, b_{ij}, I_i, τ are ω -periodic functions
- $\mathcal{M} = diag(a_1^-, \dots, a_N^-) \left[b_{ij}^+ F_j\right]$ is an M-matrix

Then

the $\omega\text{-periodic}$ Xu-Wu model has a unique $\omega\text{-periodic}$ solution which is globally exponentially stable.

Xu-Wu assume:

- a_i, b_{ij}, I_i, τ are ω -periodic functions
- $\exists \bar{d} > 0: d_i a_i^- > \sum_{i=1}^N d_j b_{ij}^+ F_j, i = 1, \dots, N \quad (\Leftrightarrow \mathcal{M} \text{ is an } M\text{-matrix})$
- $\hat{a}_{i} > F_{i} \sum_{j=1}^{N} |\hat{b}_{ji}|, i = 1, \dots, N, \text{ where } \hat{a}_{i} := \frac{1}{\omega} \sum_{n=1}^{\omega-1} a_{i}(n), \hat{b}_{ij} := \frac{1}{\omega} \sum_{n=1}^{\omega-1} b_{ij}(n)$

Stability of Hopfield models | Existence of periodic orbits for the Xu-Wu model

Proof

• Previous Corollary \Rightarrow there are $\mu > 0, C > 1$ such that

$$\|\overline{x}_m(\cdot, n, \overline{\alpha}) - \overline{x}_m(\cdot, n, \overline{\alpha}^*)\| \leqslant C e^{-\mu(m-n)} \|\overline{\alpha} - \overline{\alpha}^*\|$$

- choose $k \in \mathbb{N}$ such that $C e^{-\mu k\omega} < 1$
- Define $P: X^N \to X^N$ by $P(\overline{\alpha}) = \overline{x}_{n+\omega}(\cdot, n, \overline{\alpha})$
- $||P^k(\overline{\alpha}) P^k(\overline{\alpha}^*)|| \le C e^{-\mu k\omega} ||\overline{\alpha} \overline{\alpha}^*||$
- P^k contraction on $X^N \Rightarrow$ there is a unique $\overline{\varphi} \in X^N$ such that $P^k(\overline{\varphi}) = \overline{\varphi} \Leftrightarrow \overline{x}_{n+\omega}(\cdot, n, \overline{\varphi}) = \overline{\varphi}$
- $\overline{x}(m, n, \overline{\varphi}) = \overline{x}(m, n, \overline{x}_{n+\omega}(\cdot, n, \overline{\varphi})) = \overline{x}(m+\omega, n, \overline{\varphi})$
- $\overline{x}(m, n, \overline{\varphi})$ is a ω -periodic solution and all other solutions converge to it with exponential rates.

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Thank you

A.Bento, J.J.Oliveira, C.Silva, Nonuniform behavior and stability of Hopfield neural networks with delays Nonlinearity 30 (2017) 3088-3103.